

$$① |q_1| \cdot q_2 \cdot (x-d)^2 - |q_2| \cdot q_1 \cdot x^2 = 0$$

$$|q_1| \cdot x^2 - |q_1| \cdot 2dx + |q_1| \cdot d^2 - |q_2| \cdot x^2 = 0$$

$$(|q_1| - |q_2|) \cdot x^2 - |q_1| \cdot 2dx + |q_1| \cdot d^2 = 0 \quad /: |q_1|$$

$$\left(1 - \frac{|q_2|}{|q_1|}\right) \cdot x^2 - 2dx + d^2 = 0$$

kvadratická rovnica

1. ak  $|q_2| > |q_1| \Rightarrow \sqrt{p} > 1 \Rightarrow \frac{d}{1-\sqrt{p}}$  je záporné ~~pred~~ pred  $q_1$

$\frac{d}{1+\sqrt{p}}$  je kladné (medzi  $q_1$  a  $q_2$ )

2. ak  $|q_2| < |q_1| \Rightarrow \sqrt{p} < 1 \Rightarrow \frac{d}{1-\sqrt{p}}$  je kladné (—|—)

$\frac{d}{1+\sqrt{p}}$  je kladné (za  $q_2$ )

3. ak  $|q_2| = |q_1| \Rightarrow$  riešenie  $\frac{d}{2}$

③ obežná rýchlosť  $\rightarrow$  odstredivá sila = elektrickej

$$\hookrightarrow F = m \cdot a$$

$$\downarrow$$

~~odstredivá~~ ~~zrych.~~  $\frac{v^2}{r} \cdot r$   
 dostredivá

$$v = \omega \cdot r \Rightarrow$$

$$\frac{v^2}{r} = \frac{\omega^2 r^2}{r} = \frac{\omega^2}{r}$$

$\Rightarrow$  treba si zapamätat

$$a = \omega^2 \cdot r = \frac{v^2}{r}$$


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dostredivé zrychlenie

$$a = \frac{v^2}{r} \Rightarrow F = m \cdot \frac{v^2}{r} \Rightarrow F = m \cdot \frac{v^2}{r}$$

⑥ ak  $\boxed{\text{rot } \vec{E} = 0} \Rightarrow$  rovná funkcia môže predstavovať reálne elektrostát. pole



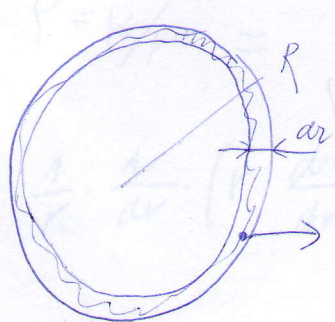
- 7, 12, 14, 15, 16, 17, 19, 20

8)  $V(r) = \frac{q \cdot e^{-ar}}{4\pi\epsilon_0 r}$   $q, a - \text{konst.}$

9)  $\rho(r) = -\frac{q \cdot e^{-\frac{2r}{a_0}}}{\pi a_0^3}$   $a_0 - \text{konst.} = r$

$$Q = \int \rho \, dV$$

AHA TAXI: 042190 7 644 777



$E \cdot \Delta S$

↳ obsah kruh. elementu, nie kruhu ⇒

$2\pi r \cdot dr$

$$\frac{Q}{4\pi\epsilon_0 \cdot r}$$

$$Q = \nabla \cdot S \Rightarrow$$

$$\frac{\nabla \cdot S}{4\pi\epsilon_0 \cdot r}$$

Prechod sférických súradníc na kartéz.

$x = r \cdot \sin \vartheta \cdot \cos \varphi$

$y = r \cdot \sin \vartheta \cdot \sin \varphi$

$z = r \cdot \cos \vartheta$

na cylindrické

$\rho = r \cdot \sin \vartheta$

$\varphi' = \varphi$

$z = r \cdot \cos \vartheta$

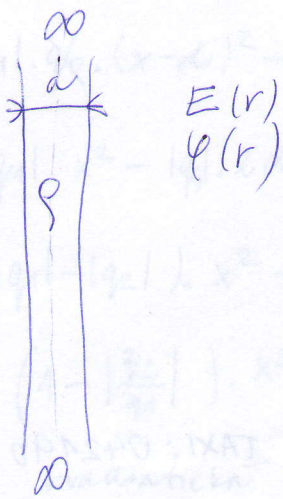
$V = (r, \varphi, \vartheta) = \frac{a \cos \vartheta}{r^2} + \frac{s}{r}$

$E = -\text{grad } V = -\frac{\partial V}{\partial r} - \frac{\partial V}{\partial \vartheta}$

10)

$\frac{1}{r} \cdot \frac{\partial}{\partial r} (r \frac{\partial V}{\partial r}) + \frac{1}{r^2} \frac{\partial}{\partial \vartheta} (r \cdot \sin \vartheta \frac{\partial V}{\partial \vartheta}) + \frac{1}{r^2 \sin^2 \vartheta} \frac{\partial^2 V}{\partial \varphi^2} = 0$





$$\textcircled{21} \left( \frac{\rho A}{4\pi\epsilon_0} e^{-ar} \right)' = \frac{A}{4\pi\epsilon_0} \cdot e^{-ar} (-a) \cdot (-a) = \dots$$

$$\Delta(xy) - \Delta z^2$$

$$\textcircled{23} \Delta y \cdot \vec{i} + \Delta x \cdot \vec{j} - 2\Delta z \cdot \vec{k} = \vec{E} \quad | \cdot (-1)!$$

$$\text{prievzet } E: E_a = \vec{E} \cdot \frac{\vec{a}}{|\vec{a}|} =$$

$$(\Delta y \cdot \vec{i} + \Delta x \cdot \vec{j} - 2\Delta z \cdot \vec{k}) \cdot (\vec{i} + 3\vec{k}) =$$

$$\frac{\Delta y - 6\Delta z}{\sqrt{10}}$$

③ obznanie: ...  
 Priemet vektora  $\vec{X}$  do smeru vektora  $\vec{y}$

$$\Rightarrow \text{poct tamne} \quad X = \vec{X} \cdot \frac{\vec{y}}{|\vec{y}|}$$

u bode?  $\nearrow$  dosadime

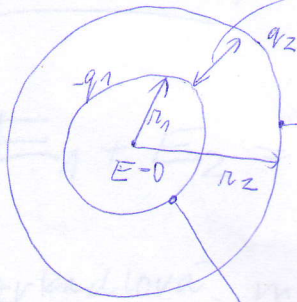
$$\textcircled{4} \text{ ak } \boxed{\text{rot } \vec{E} = 0}$$



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$$|q_1| < |q_2|$$

$$r_1 < r_2$$



$$E = ?$$

$$V = ?$$

Potencial:

$$\vec{E} = \int d\vec{E} = \frac{1}{4\pi\epsilon_0} \cdot (-q_1) \cdot \frac{1}{r^2} = \frac{1}{4\pi\epsilon_0} \cdot (-q_1) \cdot \frac{1}{r^2}$$

$$R_1 < r < (R_2, R_2) \quad \left( \frac{1}{R_1} - \frac{1}{R_2} \right)$$

$$\vec{E} = \frac{1}{4\pi\epsilon_0} \cdot \left( \frac{q_2 - q_1}{R^2} \right)$$

$$R > R_2$$

$$\hookrightarrow = \frac{1}{4\pi\epsilon_0} \cdot q_1 \left( \frac{1}{R_2} - \frac{1}{R_1} \right)$$

$$\oint \vec{E} \cdot d\vec{S} = \frac{Q_1}{\epsilon_0} \Rightarrow E = \frac{1}{4\pi\epsilon_0} \cdot \frac{q_1}{R^2}$$

nerätam

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$$P = k/r =$$

$$\frac{1}{r} \cdot \frac{d}{dr} \left( r \cdot \frac{dV}{dr} \right) = -\frac{k}{\epsilon_0 r} \Rightarrow \frac{d}{dr} \left( r \frac{dV}{dr} \right) = -\frac{k}{\epsilon_0}$$

$$-\frac{k}{\epsilon_0} r + C_1 = r \frac{dV}{dr} \Rightarrow \frac{dV}{dr} = -\frac{k}{\epsilon_0} + \frac{C_1}{r}$$

pre  $r \leq a \Rightarrow V = 0 \Rightarrow -\frac{k}{\epsilon_0} + \frac{C_1}{R} = 0 \Rightarrow C_1 = \frac{k}{\epsilon_0} \cdot a$

$$\left( V = \frac{A}{4\pi\epsilon_0} \cdot e^{-\alpha r} \right)' = \left\{ \frac{A}{4\pi\epsilon_0} \cdot e^{-\alpha r} \cdot (-\alpha) \right\}$$

$$\frac{1}{r} \cdot \frac{d}{dr} \left( r \cdot \frac{dV}{dr} \right) = +\frac{1}{\epsilon_0} \rho$$

$$\left( (-1) \cdot \frac{A \alpha}{4\pi\epsilon_0} \cdot e^{-\alpha r} \right)' = \frac{(+1) A \alpha^2}{4\pi\epsilon_0} \cdot e^{-\alpha r} \cdot r + \frac{(-1) A \alpha}{4\pi\epsilon_0} \cdot e^{-\alpha r} \Rightarrow$$

$$\hookrightarrow \left( \frac{A \alpha}{4\pi\epsilon_0} \cdot e^{-\alpha r} \cdot (\alpha \cdot r - 1) \right) \cdot \frac{1}{r} = \frac{A \alpha^2}{4\pi\epsilon_0} \cdot e^{-\alpha r} \cdot \left( \alpha - \frac{1}{r} \right)$$

pe)  $v = \omega^2 r^2 + s$ ;  $\rho = ?$

$$\frac{1}{r} \cdot \frac{d}{dr} \left( r \cdot \frac{dV}{dr} \right) = \frac{1}{r} \cdot \frac{d}{dr} \left( r \cdot 2\omega r \right) = \frac{1}{r} \cdot \frac{d}{dr} (2\omega r^2) = \frac{1}{r} \cdot (4\omega r) = \frac{4\omega}{r} \cdot \epsilon_0$$



$$E = -\text{grad}V \rightarrow \frac{a \cos \varphi}{r^2} + \frac{b}{r}$$

$$a r^2 \quad \boxed{a r^2} + b$$

$$a \cdot (25 \cdot r^2) =$$

$$\frac{1}{r^2} \cdot \frac{d}{dr} \left( r^2 \cdot \frac{d}{dr} \right)$$

$$\frac{1}{r^2} \cdot \frac{d}{dr} (r^2 \cdot 2ar) = \frac{1}{r^2} \frac{d}{dr} (2ar^3) = \frac{1}{r^2} \cdot 6ar^2 = 6a \epsilon_0$$

$$V = \frac{A}{4\pi\epsilon_0} \cdot e^{-\alpha r}$$

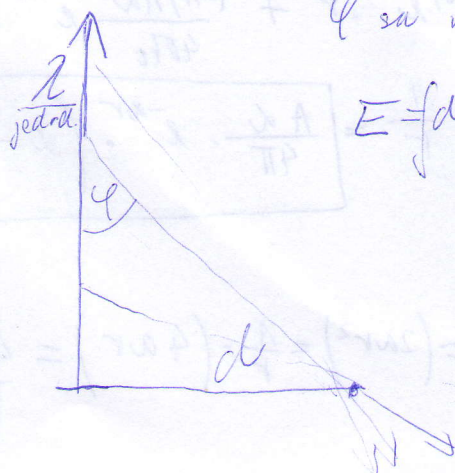
$$\frac{1}{r^2} \cdot \frac{d}{dr} \left( r^2 \cdot \frac{A(-\alpha)}{4\pi\epsilon_0} \cdot e^{-\alpha r} \right) = \frac{1}{r^2} \left( \frac{(+\alpha^2)A}{4\pi\epsilon_0} \cdot e^{-\alpha r} \cdot r^2 + \frac{(-\alpha)A}{4\pi\epsilon_0} \cdot e^{-\alpha r} \cdot \frac{2r}{r} \right) =$$

$$= \frac{\alpha A}{4\pi} \cdot e^{-\alpha r} \left( -\alpha + \frac{2}{r} \right)$$

ENERGIA DIPOLU  $\vec{p}$  v el. poli  $E$  je  $\boxed{W = -\vec{p} \cdot \vec{E}}$

$$\frac{Q}{r} \Rightarrow \vec{p} \cdot \frac{1}{r}$$

$$p = Q \cdot a$$



$\varphi$  sa meri od  $0 \rightarrow \frac{\pi}{2}$

$$E = \int dE = \frac{Q \cdot d}{4\pi\epsilon_0} \int_0^{\frac{\pi}{2}} \frac{1}{L^2} \cos \varphi d\varphi$$

$$L: \sin \ell = \frac{d}{L} \Rightarrow L = \frac{d}{\sin \ell}$$

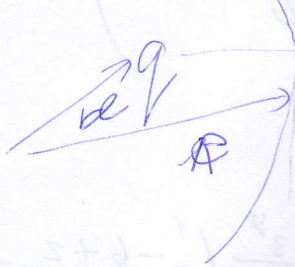
$E = ?$



$$V = \frac{\nabla}{\epsilon_0} r \quad \text{— rovninn}$$

$$E_1 + E_2 = \frac{\nabla}{\epsilon_0}$$

zrkadlová metóda



$$q' = -\frac{r}{R} \cdot q$$

vzdialenosť:  $s = \frac{r^2}{R}$

r v intenzite:  $R - l$   
 $as - R$

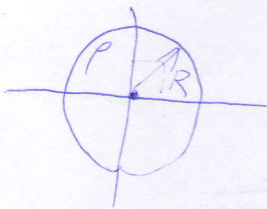
väcšie k  
menšiemu

ENERGIA el. poľa ~~u nabojom (Q)~~

$$W = \frac{\epsilon_0}{2} \int E^2 d\tau$$

$$W = \frac{1}{2} \int \rho \cdot V d\tau$$

② rovn. nabíta guľa  $R, \rho$  guľa



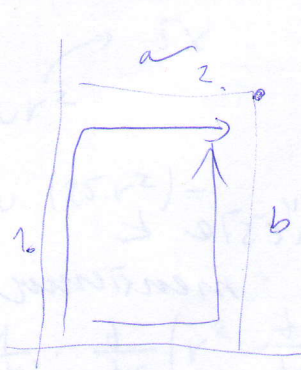
$$E = \frac{1}{4\pi\epsilon_0} \cdot \frac{Q}{r^2} = \frac{1}{4\pi\epsilon_0} \cdot \frac{\rho \cdot \frac{4\pi}{3} r^3}{r^2} = \frac{1}{\epsilon_0} \rho \cdot \frac{1}{3} r$$

$$E = \frac{1}{\epsilon_0} \cdot \frac{1}{3} \rho r \cdot \epsilon_0$$

~~~~~~~~~



①  $E = (6xy, 3x^2 - 3^y, 2) \rightarrow \text{vyp. } \int \vec{E} \cdot d\vec{e}$



a)

1.  $x=0, y: 0 \rightarrow 1$ :

$$\int \vec{E} \cdot d\vec{e} = \int E_x \cdot dx + \int E_y \cdot dy = 0 \frac{x^2}{2} \cdot y + 3x^2 y - \frac{3^y}{\ln 3} \cdot 2$$

a)  $x=0$   
 $y: 0 \rightarrow 1$   
 $E_x = 0$   
 $E_y = -3^y \cdot 2$

$$\Rightarrow \int \vec{E} \cdot d\vec{e} = \int_0^1 -2 \cdot 3^y dy = -2 \cdot \frac{3^y}{\ln 3} \Big|_0^1 = \frac{-6+2}{\ln 3} = -\frac{4}{\ln 3}$$

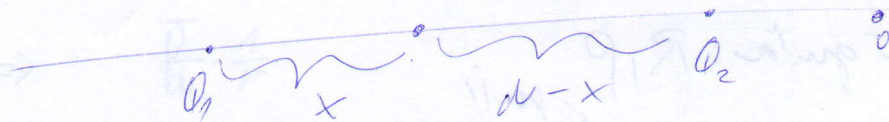
b)  $y=1$   
 $x: 0 \rightarrow 1$

$E_x = 6x$   
 $E_y = 3x^2 - 6$

$$\int_0^1 6x^2 dx = 6 \frac{x^3}{3} = 2$$

$dy = 0$  (nemění se  $\Rightarrow 0$ )

③



pre rovnakou nabítku náboje:

$\Rightarrow E_1 = E_2$

$$\frac{Q_1}{x} = \frac{Q_2}{d-x}$$

$$\frac{Q_1}{x} = \frac{Q_2}{d-x}$$

$$Q_1(d-x) = Q_2(x)$$

$$Q_1 d - Q_1 x - Q_2 x = 0$$

$$x(Q_1 + Q_2) = Q_1 \cdot d$$

$$x = \frac{Q_1}{Q_1 + Q_2} \cdot d$$